New large *N* solutions in the Sachdev-Ye-Kitaev model

Maria Tikhanovskaya

based on work in progress with I. Ya. Aref'eva, M. A. Khramtsov and I. V. Volovich

Steklov Mathematical Institute

May 29, 2018

The Sachdev-Ye-Kitaev (SYK) model

The SYK Hamiltonian

$$H_{SYK} = j_{abcd} \psi_a \psi_b \psi_c \psi_d$$

where jabed are constants taken from the Gaussian distribution

$$\langle j_{abcd}^2 \rangle = \frac{J^2}{N^3}$$

and ψ are the Majorana fermions satisfying

$$\{\psi_{\mathsf{a}},\psi_{\mathsf{b}}\}=\delta_{\mathsf{a}\mathsf{b}},\quad \mathsf{a},\mathsf{b}=1,...,\mathsf{N}$$

Free energy and replica trick

In order to evaluate the free energy in a quenched disorder system, one needs to use the replica trick

$$-\beta F = \overline{\log Z} = \lim_{M \to 0} \frac{\log Z^M}{M}$$

Free energy and replica trick

In order to evaluate the free energy in a quenched disorder system, one needs to use the replica trick

$$-\beta F = \overline{\log Z} = \lim_{M \to 0} \frac{\log Z^M}{M}$$

Take M replicas of the system

$$Z(\beta)^{M} = \int D\psi e^{-\sum_{\alpha=1}^{M} \int_{0}^{\beta} i\dot{\psi}^{\alpha}(\tau)\psi^{\alpha}(\tau) + j_{abcd}\psi^{\alpha}_{a}(\tau)\psi^{\alpha}_{b}(\tau)\psi^{\alpha}_{c}(\tau)\psi^{\alpha}_{d}(\tau)}$$

To average over disorder, we introduce bilocal fields G and Σ in order to simplify the calculations. Σ is a Lagrange multiplier that sets $G_{\alpha\beta}(\tau,\tau')=\frac{1}{N}\sum_a\psi^\alpha_a(\tau)\psi^\beta_a(\tau')$.

Free energy and replica trick

In order to evaluate the free energy in a quenched disorder system, one needs to use the replica trick

$$-\beta F = \overline{\log Z} = \lim_{M \to 0} \frac{\log \overline{Z^M}}{M}$$

Take M replicas of the system

$$Z(\beta)^{M} = \int D\psi e^{-\sum_{\alpha=1}^{M} \int_{0}^{\beta} i\dot{\psi}^{\alpha}(\tau)\psi^{\alpha}(\tau) + j_{abcd}\psi^{\alpha}_{a}(\tau)\psi^{\alpha}_{b}(\tau)\psi^{\alpha}_{c}(\tau)\psi^{\alpha}_{d}(\tau)}$$

To average over disorder, we introduce bilocal fields G and Σ in order to simplify the calculations. Σ is a Lagrange multiplier that sets $G_{\alpha\beta}(\tau,\tau')=\frac{1}{N}\sum_a\psi^\alpha_a(\tau)\psi^\beta_a(\tau')$. Integration over disorder gives

$$\overline{Z(\beta)^M} = \int DGD\Sigma \, \operatorname{Det}[\,\delta_{\alpha\beta}\partial_{ au} - \Sigma_{\alpha\beta}]^{rac{N}{2}} imes$$

$$\exp\left[-\frac{N}{2}\sum_{\alpha\beta}\int_0^\beta\int_0^\beta d\tau_1d\tau_2\left(\sum_{\alpha\beta}(\tau_1,\tau_2)G_{\alpha\beta}(\tau_1,\tau_2)-\frac{J^2}{4}G_{\alpha\beta}(\tau_1,\tau_2)^4\right)\right]$$
 saddle point eqs: $G(\omega)=\frac{1}{-i\omega-\Sigma(\omega)},\ \Sigma_{\alpha\beta}(\tau,\tau_1')=J^2_{\alpha\beta}G_{\alpha\beta}(\tau,\tau_1')^3$

IR limit

IR limit in the SYK model \iff drop ∂_{τ} from the action.

IR limit

IR limit in the SYK model \iff drop ∂_{τ} from the action. The path integral in this limit

$$\overline{Z(\beta)^M} = \int DGD\Sigma \operatorname{Det}[-\Sigma_{\alpha\beta}]^{\frac{N}{2}} \times$$

$$\exp\left[-\frac{N}{2}\sum_{\alpha\beta}\int_0^\beta\int_0^\beta d\tau_1d\tau_2\left(\Sigma_{\alpha\beta}(\tau_1,\tau_2)G_{\alpha\beta}(\tau_1,\tau_2)-\frac{J^2}{4}(G_{\alpha\beta}(\tau_1,\tau_2))^4\right)\right]$$

IR limit

IR limit in the SYK model \iff drop ∂_{τ} from the action. The path integral in this limit:

$$\overline{Z(eta)^M} = \int DGD\Sigma \ {\sf Det}[-\Sigma_{lphaeta}]^{rac{N}{2}} imes$$

$$\exp\left[-\frac{N}{2}\sum_{\alpha\beta}\int_0^\beta\int_0^\beta d\tau_1d\tau_2\left(\Sigma_{\alpha\beta}(\tau_1,\tau_2)G_{\alpha\beta}(\tau_1,\tau_2)-\frac{J^2}{4}(G_{\alpha\beta}(\tau_1,\tau_2))^4\right)\right]$$

and the saddle point equations:

$$G(\omega) = -\frac{1}{\Sigma(\omega)}, \quad \Sigma_{\alpha\beta}(\tau, \tau') = J^2 G_{\alpha\beta}(\tau, \tau')^3$$

In the IR limit the saddle point equations are exactly solvable

$$G_{lphaeta}(au) = extstyle{m{ extstyle P}}_{lphaeta} b rac{ extstyle extsty$$

In the IR limit the saddle point equations are exactly solvable

$$G_{lphaeta}(au) = extstyle{P_{lphaeta}} b rac{ extstyle{sgn}(au)}{|J au|^{2\Delta}}, \;\; \Delta = rac{1}{4}.$$

saddle point equations for $P_{\alpha\beta}$:

$$\sum_{\beta} P_{\alpha\beta} P_{\beta\gamma}^3 = \mathcal{C}\delta_{\alpha\gamma}$$

In the IR limit the saddle point equations are exactly solvable

$$G_{lphaeta}(au) = P_{lphaeta}brac{ extsf{sgn}(au)}{|J au|^{2\Delta}}, \;\; \Delta = rac{1}{4}.$$

saddle point equations for $P_{\alpha\beta}$:

$$\sum_{\beta} P_{\alpha\beta} P_{\beta\gamma}^3 = \mathcal{C}\delta_{\alpha\gamma}$$

▶ RD ansatz: $P_{\alpha\beta} = \delta_{\alpha\beta}$, [Kitaev'15; Polchinski,Rosenhaus'16; Maldacena,Stanford'16;...]

In the IR limit the saddle point equations are exactly solvable

$$G_{lphaeta}(au) = P_{lphaeta}brac{ extsf{sgn}(au)}{|J au|^{2\Delta}}, \;\; \Delta = rac{1}{4}.$$

saddle point equations for $P_{\alpha\beta}$:

$$\sum_{\beta} P_{\alpha\beta} P_{\beta\gamma}^3 = \mathcal{C} \delta_{\alpha\gamma}$$

- ▶ RD ansatz: $P_{\alpha\beta} = \delta_{\alpha\beta}$, [Kitaev'15; Polchinski,Rosenhaus'16; Maldacena,Stanford'16;...]
- RSB ansatz:
 - $P_{\alpha\beta}$ = any skew-symmetric matrix [0-dim model: Aref'eva, Volovich'18]



In the IR limit the saddle point equations are exactly solvable

$$G_{lphaeta}(au) = P_{lphaeta}brac{\mathsf{sgn}(au)}{|J au|^{2\Delta}}, \;\; \Delta = rac{1}{4}.$$

saddle point equations for $P_{\alpha\beta}$:

$$\sum_{\beta} P_{\alpha\beta} P_{\beta\gamma}^3 = \mathcal{C}\delta_{\alpha\gamma}$$

- ▶ RD ansatz: $P_{\alpha\beta} = \delta_{\alpha\beta}$, [Kitaev'15; Polchinski,Rosenhaus'16; Maldacena,Stanford'16;...]
- RSB ansatz:
 - $P_{\alpha\beta} =$ any skew-symmetric matrix [0-dim model: Aref'eva, Volovich'18]
 - $P_{\alpha\beta}$ = Parisi martix [present work]



Parisi matrices are constructed of m_i blocks, where i = 1, ..., M and I parameters under the following conditions [Parisi'72]:

$$P_{l+1} = \begin{pmatrix} P_{l} & a_{l} \, \mathcal{J}_{l} & \dots & a_{l} \, \mathcal{J}_{l} \\ a_{l} \, \mathcal{J}_{l} & P_{l} & \dots & a_{l} \, \mathcal{J}_{l} \\ & \dots & \dots \\ a_{l} \, \mathcal{J}_{l} & a_{l} \, \mathcal{J}_{l} & \dots & P_{l} \end{pmatrix}, \qquad \mathcal{J}_{l} = \begin{pmatrix} 1 & 1 & \dots & 1 \\ 1 & 1 & \dots & 1 \\ & \dots & \dots & \\ 1 & 1 & 1 & 1 \end{pmatrix}$$

Parisi matrices are constructed of m_i blocks, where i = 1, ..., M and I parameters under the following conditions [Parisi'72]:

$$P_{l+1} = \begin{pmatrix} P_{l} & a_{l} \mathcal{J}_{l} & \dots & a_{l} \mathcal{J}_{l} \\ a_{l} \mathcal{J}_{l} & P_{l} & \dots & a_{l} \mathcal{J}_{l} \\ & \dots & \dots \\ a_{l} \mathcal{J}_{l} & a_{l} \mathcal{J}_{l} & \dots & P_{l} \end{pmatrix}, \quad \mathcal{J}_{l} = \begin{pmatrix} 1 & 1 & \dots & 1 \\ 1 & 1 & \dots & 1 \\ & \dots & \dots & \\ 1 & 1 & 1 & 1 \end{pmatrix}$$

In the case of M = 4 it looks like

$$P_4 = \begin{pmatrix} a_0 & a_1 & a_2 & a_2 \\ a_1 & a_0 & a_2 & a_2 \\ a_2 & a_2 & a_0 & a_1 \\ a_2 & a_2 & a_1 & a_0 \end{pmatrix}$$

The saddle point equations for the parameters of the matrix

$$C = a_0^4 + \sum a_j^4 (m_{j+1} - m_j)$$

$$a_j a_0^3 + a_0 a_j^3 + \sum (a_i a_j^3 + a_j a_i^3) (m_{i+1} - m_i) = m_j a_j^4 - \sum a_i^4 (m_{i+1} - m_i)$$

The saddle point equations for the parameters of the matrix

$$\mathcal{C} = a_0^4 + \sum_j a_j^4 (m_{j+1} - m_j)$$

$$a_j a_0^3 + a_0 a_j^3 + \sum_j (a_i a_j^3 + a_j a_i^3) (m_{i+1} - m_i) = m_j a_j^4 - \sum_j a_i^4 (m_{i+1} - m_i)$$

In the limit $M \rightarrow 0$ the saddle point eqs become

$$\mathcal{C} = a_0^4 - \langle a^4 \rangle$$

$$a(u)[a_0^3 - \langle a^3 \rangle] + a^3(u)[a_0 - \langle a \rangle] = \int_0^u [a(v) - a(u)][a^3(v) - a^3(u)] dv$$

where the angular brackets denote the average over v

$$\int_0^1 a^p(v) \, dv \equiv \langle a^p \rangle$$

One-step ansatz

To solve the equations, we need to make some assumption. Let the function a(u) be:

$$a(u) = A_0 + A_1 \theta(u - \mu)$$

where μ is the breakpoint and which is considered in [Georges,Parcollet,Sachdev'99] in the context of the original SY-model

One-step ansatz

To solve the equations, we need to make some assumption. Let the function a(u) be:

$$a(u) = A_0 + A_1 \theta(u - \mu)$$

where μ is the breakpoint and which is considered in [Georges, Parcollet, Sachdev'99] in the context of the original SY-model The saddle point equations

$$a_0^4 - (A_0 + A_1)^4 + A_1 (2A_0 + A_1) (2A_0^2 + 2A_1A_0 + A_1^2) \mu = \mathcal{C}$$

$$A_0(a_0A_0^2 + a_0^3 + A_1^3(\mu - 1) + 3A_0A_1^2(\mu - 1) + 4A_0^2A_1(\mu - 1) - 2A_0^3) = 0;$$

$$A_1(A_1^2(a_0 + A_0(3\mu - 7)) + 3A_0A_1(a_0 + A_0(\mu - 3)) + 3a_0A_0^2$$

$$+ a_0^3 + A_1^3(\mu - 2) - 4A_0^3) = 0$$

Classes of solutions for a(u)

The saddle point equations admit solutions

- 1. Replica-diagonal solution: $A_0 = 0$, $A_1 = 0$.
- 2. Replica-symmetric solution: $A_0 = a_0$, $A_1 = 0$. It cannot be a solution of the full SYK model, since it requires $\mathcal{C} = 0$.
- 3. Replica-symmetric complex-valued solutions:

$$A_0 = \frac{1}{4} \left(-1 \pm i\sqrt{7} \right)$$

$$A_1 = 0$$

4. RSB simple solution: $A_0 = 0$ which provides

$$A_1^2 a_0 + a_0^3 + A_1^3 (\mu - 2) = 0$$
$$a_0^3 + a_0 A_1^2 + A_1^3 (\mu - 2) = 0$$

5. More complex solutions: $A_0 \neq 0$ and $A_1 \neq 0 \Rightarrow$ numeric calculations

Free energy on the RSB solution

The free energy is:

$$-\beta F = \lim_{M \to 0} \frac{1}{M} \log \overline{Z^M}$$

The replica and time dependencies separate

$$\frac{2}{\textit{N}}\textit{S}_{\textit{M}} = -\text{Tr}\log[-\left(\Sigma_{\alpha\beta}\right)]$$

$$+ \int_0^\beta \int_0^\beta d\tau_1 d\tau_2 \sum_{\alpha\beta} \left(\sum_{\alpha\beta} (\tau_1, \tau_2) G_{\alpha\beta}(\tau_1, \tau_2) - \frac{J^2}{q} (G_{\alpha\beta}(\tau_1, \tau_2))^q \right) =$$

$$- M \log \det[-J^2 g_c(\tau, \tau')^{q-1}] - \frac{\Lambda}{q} \left(\log \det[\mathcal{C}^{1/q-1} Q^{\circ (q-1)}] - \frac{1-q}{q} M \right)$$

where $\Lambda \sim \beta J/\pi$. The only one term we have to think about in the $M \rightarrow 0$ limit gives:

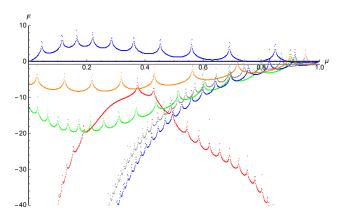
$$\log \det [\mathfrak{C}^{1/q-1}Q^{\circ (q-1)}] = \frac{1-q}{q} \log \mathfrak{C} + \log (a_0^{q-1} - \langle a^{q-1} \rangle)$$

$$-\int_0^1 \frac{dv}{v^2} \log \frac{a_0^{q-1} - \langle a^{q-1} \rangle - [a^{q-1}](v)}{a_0^{q-1} - \langle a^{q-1} \rangle} + \frac{a^{q-1}(0)}{a_0^{q-1} - \langle a^{q-1} \rangle}$$

other terms are the same as in the RD case

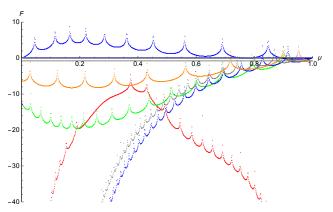
Free energy on the RSB solution

The plot of the replica dependent term of the free energy as a function of breakpoint at $a_0=0.7$ and $\beta J\sim 10$



Free energy on the RSB solution

The plot of the replica dependent term of the free energy as a function of breakpoint at $a_0=0.7$ and $\beta J\sim 10$



- 1. saddle points are complex valued
- 2. a landscape of metastable states

Comparison of RSB solution with replica-diagonal solution

The expression for the free energy:

▶ RD case low temperature expansion [Maldacena,Stanford'16;Kitaev'17]:

$$\beta F = \beta E_0 - s_0 - \frac{c}{2\beta}$$

 E_0 is the vacuum energy, s_0 - zero temperature entropy, $c \sim N/J$ is the specific heat

Comparison of RSB solution with replica-diagonal solution

The expression for the free energy:

► RD case low temperature expansion [Maldacena,Stanford'16;Kitaev'17]:

$$\beta F = \beta E_0 - s_0 - \frac{c}{2\beta}$$

 E_0 is the vacuum energy, s_0 - zero temperature entropy, $c \sim N/J$ is the specific heat

RSB case

$$\beta F = \beta E_0 + \beta E_0^{RSB} - s_0 - \frac{c}{2\beta}$$

where E_0^{RSB} arises from replicas.

Reparametrization invariance

Reparametrization invariance of the system changes from the replica-diagonal case

$$G_{\alpha\beta}(\tau,\tau') = f_{\alpha}'(\tau)^{\Delta} f_{\beta}'(\tau')^{\Delta} G_{\alpha\beta}(f_{\alpha}(\tau),f_{\beta}(\tau'))$$

$$\Sigma_{\alpha\beta}(\tau,\tau') = f_{\alpha}'(\tau)^{1-\Delta} f_{\beta}'(\tau')^{1-\Delta} \Sigma_{\alpha\beta}(f_{\alpha}(\tau),f_{\beta}(\tau'))$$

where $f_{\alpha}(\tau) \in \frac{\text{diff}(S^1)^{\times M}}{SL(2,\mathbb{R})}$ – expanded reparametrization symmetry. Each replica produces a soft mode with the total action

$$S_{local} \sim eta J \int_{0}^{2\pi} \sum_{lpha} {\sf Sch} \left({\sf tan} \left(f_{lpha}(heta)
ight), heta
ight) \, d heta$$

Results

- We constructed the new large N solutions of the SYK model
- ► The part of the free energy which is depend on replicas, has several metastable phases
- ► The factorized ansatz $G_{\alpha\beta}(\tau) = P_{\alpha\beta}g(\tau)$ gives a correction to the ground state energy $\beta F = \beta E_0 + \beta E_0^{RSB} s_0 \frac{c}{2\beta}$
- ► The factorized ansatz breaks spontaneously the reparmetrization symmetry ⇒ new solutions can be generated

Results

- We constructed the new large N solutions of the SYK model
- ► The part of the free energy which is depend on replicas, has several metastable phases
- ► The factorized ansatz $G_{\alpha\beta}(\tau) = P_{\alpha\beta}g(\tau)$ gives a correction to the ground state energy $\beta F = \beta E_0 + \beta E_0^{RSB} s_0 \frac{c}{2\beta}$
- ► The factorized ansatz breaks spontaneously the reparmetrization symmetry ⇒ new solutions can be generated

Thank you for your attention